



**TANGO**  
Device  
Server

# **CompactPCICrate User's Guide**

## **CompactPCICrate Class**

**Revision: release\_2\_1\_2 - Author: elattaoui  
Implemented in C++**

### **Introduction:**

DeviceServer used to remotely access the operating system through TANGO.

### **Class Inheritance:**

- Tango::Device\_3Impl
  - CompactPCICrate

### **Properties:**

**There is no Class properties.  
There is no Device Properties.**

## Attributes:

Scalar Attributes			
Attribute name	Data Type	R/W Type	Expert
<b>upTime</b>	DEV_STRING	READ	No
<b>time:</b> gives the date of the day, and the current CPU hour.	DEV_STRING	READ	No
<b>secondSince1970:</b> gives the number of seconds elapsed since 1970	DEV_LONG	READ	No
<b>cpuCharge:</b> The cpu usage in percent.	DEV_SHORT	READ	No
<b>physicalMemoryUsed:</b> Total physical memory used (%).	DEV_DOUBLE	READ	No
<b>swapUsed:</b> Swap used (%).	DEV_DOUBLE	READ	No
<b>virtualMemoryUsed:</b> Virtual memory used in percent.	DEV_DOUBLE	READ	No
<b>sortProcessesListBy:</b> Specifies how to sort the processes list. Expected values : -> For *nix OS - PID - EXENAME: lexicographic order - DEFAULT : length of the entire string -> For win32 : above list + - MEMORY (actual process memory used) - PEAK (max memory used per process) - THREAD (number of process threads)	DEV_STRING	WRITE	No

Spectrum Attributes			
Attribute name	Data Type	X Data Length	Expert
<b>servicesList:</b> Show all services stopped or running on this machine	DEV_STRING	1024	No
<b>processesList:</b> Show all processes running on this machine	DEV_STRING	1024	No
<b>doubledProcessesList:</b> List of doubled processes if any.	DEV_STRING	1024	No

## Commands:

More Details on commands....

## Device Commands for Operator Level

Command name	Argument In	Argument Out
<b>Init</b>	DEV_VOID	DEV_VOID
<b>State</b>	DEV_VOID	DEV_STATE
<b>Status</b>	DEV_VOID	CONST_DEV_STRING
<b>ImmediateShutdown</b>	DEV_VOID	DEV_VOID
<b>DifferedShutdown</b>	DEV_SHORT	DEV_VOID
<b>ShutdownAndPowerOff</b>	DEV_VOID	DEV_VOID
<b>ShellExe</b>	DEVVAR_STRINGARRAY	DEV_VOID
<b>Reboot</b>	DEV_VOID	DEV_VOID
<b>KillProcessByPID</b>	DEV_ULONG	DEV_VOID
<b>StartService</b>	DEV_STRING	DEV_VOID
<b>ReStartService</b>	DEV_STRING	DEV_VOID
<b>ReStartStarterService</b>	DEV_VOID	DEV_VOID
<b>ReStartNTPDaemon</b>	DEV_VOID	DEV_VOID
<b>GetOSVersion</b>	DEV_VOID	DEV_STRING
<b>SearchProcesses</b>	DEV_STRING	DEVVAR_STRINGARRAY
<b>ProcessInfos</b>	DEV_ULONG	DEVVAR_STRINGARRAY
<b>ProcessModules</b>	DEV_ULONG	DEVVAR_STRINGARRAY

### 1 - Init

- **Description:** This commands re-initialise a device keeping the same network connection.  
After an Init command executed on a device, it is not necessary for client to re-connect to the device.  
This command first calls the device *delete\_device()* method and then execute its *init\_device()* method.  
For C++ device server, all the memory allocated in the *nit\_device()* method must be freed in the *delete\_device()* method.  
The language device desctructor automatically calls the *delete\_device()* method.
- **Argin:**  
**DEV\_VOID** : none.
- **Argout:**  
**DEV\_VOID** : none.
- **Command allowed for:**

## 2 - State

- **Description:** This command gets the device state (stored in its *device\_state* data member) and returns it to the caller.
- **Argin:**  
**DEV\_VOID** : none.
- **Argout:**  
**DEV\_STATE** : State Code
- **Command allowed for:**

## 3 - Status

- **Description:** This command gets the device status (stored in its *device\_status* data member) and returns it to the caller.
- **Argin:**  
**DEV\_VOID** : none.
- **Argout:**  
**CONST\_DEV\_STRING** : Status description
- **Command allowed for:**

## 4 - ImmediateShutdown

- **Description:** Initiates an immediate shutdown of the operating system As this is not possible to get a remote indication of the real state of shutdown, , you should wait a few seconds before turning power off the crate, so that you let the system gracefully shutdown
- **Argin:**  
**DEV\_VOID** :
- **Argout:**  
**DEV\_VOID** :
- **Command allowed for:**

## 5 - DifferedShutdown

- **Description:** Initiates a shutdown after the number of seconds given as argument You should wait a few seconds before turning power off the crate to let the system gracefully shutdown
- **Argin:**  
**DEV\_SHORT** : number of seconds before shutdown
- **Argout:**  
**DEV\_VOID** :
- **Command allowed for:**

## 6 - ShutdownAndPowerOff

- **Description:** Does an immediate shutdown and switch power off if possible Of course, the system must support the power-off feature.
- **Argin:**  
DEV\_VOID :
- **Argout:**  
DEV\_VOID :
- **Command allowed for:**

## 7 - ShellExe

- **Description:** execute a shell script with arguments as this : "cmd", "arg1 arg2 ..." For Linux, you can add the '&' character to avoid CORBA timeout !
- **Argin:**  
DEVVAR\_STRINGARRAY : path to the shell script,argument1, argument2 , ..]
- **Argout:**  
DEV\_VOID :
- **Command allowed for:**

## 8 - Reboot

- **Description:** Reboot system
- **Argin:**  
DEV\_VOID :
- **Argout:**  
DEV\_VOID :
- **Command allowed for:**

## 9 - KillProcessByPID

- **Description:** Kill a process identified by its pID.
- **Argin:**  
DEV\_ULONG : process ID
- **Argout:**  
DEV\_VOID : no argout
- **Command allowed for:**

## 10 - StartService

- **Description:** Start the specified service
- **Argin:**  
DEV\_STRING : name of the service to start
- **Argout:**  
DEV\_VOID : no argout
- **Command allowed for:**

## 11 - ReStartService

- **Description:** Stop and start the specified service
- **Argin:**  
DEV\_STRING : name of the service to restart
- **Argout:**  
DEV\_VOID : no argout
- **Command allowed for:**

## 12 - ReStartStarterService

- **Description:** ReStart the local starter service
- **Argin:**  
DEV\_VOID : no argin
- **Argout:**  
DEV\_VOID : no argout
- **Command allowed for:**

## 13 - ReStartNTPDaemon

- **Description:** ReStarts the NTP Daemon service
- **Argin:**  
DEV\_VOID : no argin
- **Argout:**  
DEV\_VOID : no argout
- **Command allowed for:**

## 14 - GetOSVersion

- **Description:** Returns the OS version on which the device is running
- **Argin:**  
DEV\_VOID : no argin
- **Argout:**  
DEV\_STRING : OS version
- **Command allowed for:**

## 15 - SearchProcesses

- **Description:** Returns process(es) matching the pattern. This command is case insensitive.
- **Argin:**  
DEV\_STRING : Pattern to found
- **Argout:**  
DEVVAR\_STRINGARRAY : List of process(es) matching the pattern
- **Command allowed for:**

## 16 - ProcessInfos

- **Description:** Return process informations such as : - exe name - command line - memory usage - peak memory usage - started at - ended at - ...
- **Argin:**  
DEV\_ULONG : Process PID
- **Argout:**  
DEVVAR\_STRINGARRAY : Process Informations
- **Command allowed for:**

## 17 - ProcessModules

- **Description:** Process dlls loaded
- **Argin:**  
DEV\_ULONG : Process pid
- **Argout:**  
DEVVAR\_STRINGARRAY : List of loaded modules
- **Command allowed for:**

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# CompactPCICrate Device Commands Description CompactPCICrate Class

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**DEV\_STATE** : State Code
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DEVVAR\_STRINGARRAY : List of loaded modules
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