





TANGO Device Server

XMCD User's Guide

XMCD Class

Revision: release_1_3_2 - Author: malik Implemented in C++

Introduction:

X Ray Magnetic Dichroism

Class Inheritance:

Tango::Device_3ImplXMCD

Properties:

Device Properties				
Property name	Property name Property type Description			
MagFieldProxy	Tango::DEV_STRING	the device name of the associated BruckerBTPS		
CCDProxy	Tango::DEV_STRING	the device name of the associated CCD		
Delay	Tango::DEV_DOUBLE	time (in seconds) to wait after each write operation on the MagFieldProxyDevice		
Current	Tango::DEV_DOUBLE	initial value of 'current' attribute after INIT		
NbIteration	Tango::DEV_LONG	initial value of 'nbIteration' attribute after INIT		

Device Properties Default Values:

Property Name	Default Values	
MagFieldProxy	No default value	
CCDProxy	No default value	
Delay	No default value	
Current	No default value	
NbIteration	No default value	

There is no Class properties.

States:

States		
Names	Descriptions	
RUNNING	an acquisition is currently running	
FAULT	either one of the underlying device is in FAULT, either an error occured during the sequence	
STANDBY	waiting for the START command	

Attributes:

Scalar Attributes				
Attribute name	Data Type	R/W Type	Expert	
current: the current value applied to the MagFieldProxy device	DEV_DOUBLE	READ_WRITE	No	
nbIteration : the number of iterations to be done for a complete sequence	DEV_LONG	READ_WRITE	No	
currentIteration : if an acquisition is running, this corresponds to the current iteration of the acquisition sequence	DEV_LONG	READ	No	
delay: the time to wait after the magnetic field has changed	DEV_DOUBLE	READ_WRITE	No	

Spectrum Attributes					
Attribute name	Data Type	X Data Length	Expert		
xmcdSpectrum: the result of the computation	DEV_DOUBLE	131072	No		

Commands:

More Details on commands....

Device Commands for Operator Level				
Command name Argument In Argument Out				
Init	DEV_VOID	DEV_VOID		
State	DEV_VOID	DEV_STATE		
Status	DEV_VOID	CONST_DEV_STRING		
Start	DEV_VOID	DEV_VOID		
Stop	DEV_VOID	DEV_VOID		
Iterate	DEV_VOID	DEV_VOID		

1 - Init

Description: This commands re-initialise a device keeping the same network connection.
 After an Init command executed on a device, it is not necessary for client to re-connect to the device.
 This command first calls the device delete_device() method and then execute its init_device() method.

 For C++ device server, all the memory allocated in the nit_device() method must be freed in the delete_device() method.
 The language device descructor automatically calls the delete_device() method.

• Argin:

DEV_VOID: none.

• Argout:

DEV_VOID : none.

Command allowed for: Tango::RUNNING O Tango::FAULT Tango::STANDBY 2 - State **Description:** This command gets the device state (stored in its *device_state* data member) and returns it to the caller. DEV_VOID: none. Argout: **DEV_STATE**: State Code **Command allowed for:** Tango::RUNNING Tango::FAULT C Tango::STANDBY 3 - Status **Description:** This command gets the device status (stored in its *device_status* data member) and returns it to the caller. **Argin: DEV_VOID** : none. Argout: CONST_DEV_STRING: Status description Command allowed for: Tango::RUNNING O Tango::FAULT Tango::STANDBY 4 - Start Description: starts an acquisition sequence Argin: $DEV_VOID:$ Argout: DEV_VOID: Command allowed for: Tango::RUNNING Tango::FAULT C Tango::STANDBY

	5 - Stop
•	Description: stops the acquisition sequence which is currently running
•	Argin: DEV_VOID:
•	Argout: DEV_VOID:
• 0 0 0	Command allowed for: Tango::RUNNING Tango::FAULT Tango::STANDBY
	6 - Iterate
•	Description: execute one XMCD iteration
•	Argin: DEV_VOID:
•	Argout: DEV_VOID:
• 0 0 0	Command allowed for: Tango::RUNNING Tango::FAULT Tango::STANDBY
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There is no Class properties.

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State	DEV_VOID	DEV_STATE
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Start	DEV_VOID	DEV_VOID
Stop	DEV_VOID	DEV_VOID
Iterate	DEV_VOID	DEV_VOID

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• Argout:

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	5 - Stop
•	Description: stops the acquisition sequence which is currently running
•	Argin: DEV_VOID:
•	Argout: DEV_VOID:
• 0 0 0	Command allowed for: Tango::RUNNING Tango::FAULT Tango::STANDBY
	6 - Iterate
•	Description: execute one XMCD iteration
•	Argin: DEV_VOID:
•	Argout: DEV_VOID:
• 0 0 0	Command allowed for: Tango::RUNNING Tango::FAULT Tango::STANDBY
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TANGO Device Server

XMCD Device Commands Description XMCD Class

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1 - Init

• **Description:** This commands re-initialise a device keeping the same network connection. After an Init command executed on a device, it is not necessary for client to re-connect to the device

This command first calls the device *delete_device()* method and then execute its *init_device()* method.

For C++ device server, all the memory allocated in the *nit_device()* method must be freed in the *delete_device()* method.

The language device descructor automatically calls the *delete_device()* method.

• Argin:

DEV_VOID: none.

• Argout:

DEV VOID: none.

- Command allowed for:
 - Tango::RUNNINGTango::FAULT

○ Tango::STANDBY

2 - State

- **Description:** This command gets the device state (stored in its *device_state* data member) and returns it to the caller.
- Argin:

DEV_VOID: none.

• Argout:

DEV_STATE: State Code

• Command allowed for:

○ Tango::RUNNING

O Tango::FAULT

○ Tango::STANDBY

3 - Status

- **Description:** This command gets the device status (stored in its *device_status* data member) and returns it to the caller.
- Argin:

DEV_VOID: none.

• Argout:

CONST_DEV_STRING: Status description

• Command allowed for:

○ Tango::RUNNING

○ Tango::FAULT

○ Tango::STANDBY

4 - Start

- **Description:** starts an acquisition sequence
- Argin:

 $DEV_VOID:$

• Argout:

DEV VOID:

• Command allowed for:

○ Tango::RUNNING

○ Tango::FAULT

○ Tango::STANDBY

5 - Stop

- **Description:** stops the acquisition sequence which is currently running
- Argin:

DEV_VOID:

• Argout:

$DEV_VOID:$ Command allowed for: O Tango::RUNNING ○ Tango::FAULT O Tango::STANDBY 6 - Iterate • **Description:** execute one XMCD iteration • Argin: DEV_VOID: • Argout: $DEV_VOID:$ • Command allowed for: ○ Tango::RUNNING ○ Tango::FAULT ○ Tango::STANDBY **ESRF** - Software Engineering Group